

V6

ACCESSORIES MANUAL

MODBUS RTU BOARD



Programming and Software Manual

Edition: June 2023

Rev. A

ABOUT THIS DOCUMENT

COMPATIBILITY

This manual is suitable for Modbus RTU Card with Ground Fault.

These cards are suitable for use with V6 soft starters.

The available features may vary according to the model and version of the starter.

DISCLAIMER

The examples and diagrams in this manual are included solely for illustrative purposes. The information contained in this manual is subject to change at any time and without prior notice. In no event will responsibility or liability be accepted for direct, indirect or consequential damages resulting from the use or application of this equipment.

Failure to follow the information and instructions in this manual will void the warranty.

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POWER ELECTRONICS V6

REVISIONS CONTROL

| DATE | REVISION | DESCRIPTION |
|------------|----------|----------------|
| 30/06/2023 | Α | First edition. |

The equipment and technical documentation are periodically updated. Power Electronics reserves the right to modify all or part of the contents of this manual without previous notice. To consult the most updated information of this product, you may access our website www.power-electronics.com, where the latest version of this manual can be downloaded. The reproduction or distribution of the present manual is strictly forbidden, unless express authorization from Power Electronics.

SAFETY SYMBOLS

Always follow safety instructions to prevent accidents and potential hazards from occurring.

In this manual, safety messages are classified as follows:



NOTICE

Indicates a hazard that may cause personal injury or death.



CAUTION

Indicates a hazard that may damage the equipment or installation.



WARNING

Provides helpful information.

Other symbols used in this manual for safety messages are the following:



Hot surface. Be careful and follow the instructions to avoid burns and personal injuries.



Risk of fire. Be careful and follow the instructions to prevent causing an unintentional fire.



Energy storage timed discharge. Wait for the indicated time to avoid electrical hazards.



Caution, risk of hearing damage. Wear hearing protection.

Warnings

It is the installer's responsibility to follow all instructions in this manual and to follow correct electrical practice.



WARNING

For your safety, isolate the soft starter completely from mains voltage before attaching or removing accessories.



WARNING

Inserting foreign objects or touching the inside of the starter while the expansion port cover is open may endanger personnel, and can damage the starter.

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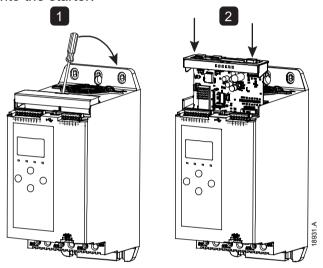
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1 INSTALLATION

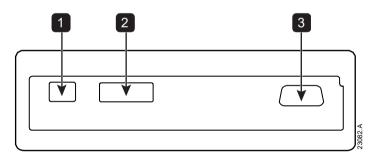


Installing the expansion card

- 1. Push a small flat-bladed screwdriver into the slot in the centre of the expansion port cover, and ease the cover away from the starter.
- 2. Line up the card with the expansion port. Gently push the card along the guide rails until it clicks into the starter.



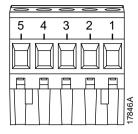
Connections



| 1 | 2 pin connector for ground fault CT (selected models) |
|---|---|
| 2 | Modbus network connection |
| 3 | DB9 connector for optional remote keypad |

Connecting to the communication network

After the card is in place, control power can be restored and field wiring can be connected via the 5-way connector plug.



| Pin | Function |
|------|----------|
| 1, 2 | Data A |
| 3 | Common |
| 4, 5 | Data B |

2 DEVICE CONFIGURATION



Configure network settings via the starter

Network communication parameters for the card should be set via the soft starter (via the Main Menu or by uploading a configuration file via USB Save & Load). For details on how to configure the soft starter, refer to the soft starter user manual.

| Parameter | Parameter name | Description | | | |
|-----------|------------------|---|--|--|--|
| 12A | Modbus Address | Sets the Modbus RTU network address for the soft starter. | | | |
| 12B | Modbus Baud Rate | Selects the baud rate for Modbus RTU communications. | | | |
| 12C | Modbus Parity | Selects the parity for Modbus RTU communications. | | | |
| 12D | Modbus Timeout | Selects the timeout for Modbus RTU communications. | | | |



NOTICE

The Modbus RTU Card will read communications parameter settings from the soft starter when control power is applied. If parameters are changed in the starter, control power must be cycled for the new values to take effect.

Enabling network control

The soft starter will only accept commands from the Modbus RTU Card if parameter 1A *Command Source* is set to 'Network'.



NOTICE

If the reset input is active, the starter will not operate. If a reset switch is not required, use parameter 7I to set the reset input to normally open or fit a link across terminals 10, 11 on the soft starter.

POWER ELECTRONICS V6

3 CLIENT CONFIGURATION

3

For standard Modbus 11-bit transmission, the client must be configured for 2 stop bits with no parity and 1 stop bit for odd or even parity.

For 10-bit transmission, the client must be configured for 1 stop bit.

In all cases, the client baud rate and server address must match those set in parameters 12A~12D.

The data polling interval must be long enough for the module to respond. Short polling intervals may cause inconsistent or incorrect behaviour, particularly when reading multiple registers. The recommended minimum polling interval is 100 ms.

PLC Configuration

Use the register tables below to map registers within the device to addresses within the PLC.

4 GROUND FAULT PROTECTION





NOTICE

Ground fault protection is only available on ground fault enabled cards, with soft starters running a compatible version of software. Contact your supplier for assistance

Overview

The Modbus RTU Card can detect ground current and trip before the equipment is damaged.

Ground fault protection requires a 1000:1 or 2000:1 current transformer (not supplied). The CT should be rated 1 VA or 5 VA. The soft starter can be configured to trip at 1 A~50 A. If ground fault current rises above 50 A, the soft starter will trip immediately.

Parameter 40C Ground Fault Trip Active selects when ground fault protection is active.

Connect the CT to the ground fault inputs

To use ground fault protection, a common mode current transformer (CT) must be installed around all three phases. Use a 1000:1 or 2000:1 CT with rating of 1 VA or 5 VA and set parameter 40E *Ground Fault CT Ratio* to match. Connect the CT to the ground fault terminals (G1, G2, G3).

For maximum protection, the CT should be installed on the input side of the soft starter.

Configure ground fault protection settings

Ground fault protection settings must be set in the soft starter.

| Parameter | Parameter name | Description |
|-----------|--------------------------|--|
| 40A | Ground fault trip level | Sets the trip point for ground fault current protection. |
| 40B | Ground fault trip delay | Slows the soft starter's response to ground fault, avoiding trips due to momentary fluctuations. |
| 40C | Ground fault trip active | Selects when a ground fault trip can occur. |
| 40D | Ground fault action | Selects the soft starter's response to the protection event. |
| 40E | Ground fault CT ratio | Set to match the ratio of the ground current measuring CT. |

5 OPERATION

5

The Modbus RTU Card must be controlled by a Modbus client (such as a PLC) which complies with the Modbus Protocol Specification. For successful operation, the client must also support all functions and interfaces described in this document.



NOTICE

The available features and parameter details may vary according to the model and software version of the starter. Refer to the soft starter user manual for details of parameters and supported features.

Ensuring safe and successful control

Data written to the device will remain in its registers until the data is overwritten or the device is reinitialised.

If the soft starter may be controlled via Command Override (parameter 7A) or may be disabled via the reset input (terminals 10, 11) fieldbus commands should be cleared from the registers. If a command is not cleared, it will be re-sent to the starter once fieldbus control resumes.

Feedback LEDs

| LED state | Description | |
|-----------|-----------------------------|--|
| Off | Soft starter not powered up | |
| On | Communication active | |
| Flashing | Communication inactive | |



NOTICE

If communication is inactive, the soft starter may trip on Network Communications. If parameter 6M *Network Communications* is set to 'Soft Trip and Log' or 'Trip Starter', the soft starter will require a reset.

6 MODBUS REGISTERS





NOTICE

The available features and parameter details may vary according to the model and software version of the starter. Refer to the soft starter user manual for details of parameters and supported features.



NOTICE

All references to registers mean the registers within the card unless otherwise stated.

Compatibility

The Modbus RTU Card supports two modes of operation.

- In Standard Mode, the device uses registers defined in the Modbus Protocol Specification.
- In Legacy Mode, the device uses the same registers as the clip-on Modbus Module, supplied for use with older soft starters. Some registers differ from those specified in the Modbus Protocol Specification.

Standard Mode

Command and configuration registers (read/write)

| Register | Description | Bits | Details |
|------------------|---------------------------|---------|---|
| 40001 | Command (single write) | 0 to 7 | To send a command to the starter, write the required value: 00000000 = Stop 00000001 = Start 00000100 = Reset 00001000 = Quick stop (coast to stop) 00010000 = Start using Parameter Set 1 00100000 = Start using Parameter Set 2 01000000 = Reserved 10000000 = Reserved |
| | | 8 to 14 | Reserved |
| | | 15 | Must = 1 |
| 40002 ~ 40008 | Reserved | | |

| Register | Description | Bits | Details |
|----------|--|------|--|
| | Parameter management (single or multiple read/write) | | Manage soft starter programmable parameters. |

Parameter Management

Parameters can be read from and written to the starter. The Modbus RTU protocol limits read/write operations to a maximum of 125 registers at one time. The registers must be consecutive.



CAUTION

Changing the values of the Advanced parameters (parameter group 20) may cause unpredictable behaviour in the soft starter. Consult your local supplier before adjusting the Advanced parameters.

Status reporting registers (read only)



NOTICE

For models 0064B and smaller (soft starter model ID 1~4), current reported via communications is 10 times greater than the actual value (displayed on the keypad).



NOTICE

Frequency reported via communications is 10 times greater than the actual value.

| Register | Description | Bits | Details |
|------------------|--------------------------|---------|---|
| 30003 ~ 30008 | Reserved | | |
| 30600 | Product information | 0 to 5 | Binary protocol version |
| | | 6 to 8 | Reserved |
| | | 9 to 15 | Product type code: |
| | | | 12 = n/a |
| | | | 13 = V6 |
| 30601 | Model number | 0 to 7 | Reserved |
| | | 8 to 15 | Soft starter model ID |
| 30602 | Changed parameter number | 0 to 7 | 0 = No parameters have changed 1~255 = Index number of the last parameter changed |
| | | 8 to 15 | Total number of parameters available in the starter |
| 30603 | Changed parameter value | 0 to 15 | Value of the last parameter that was changed, as indicated in register 30602 |

| Register | Description | Bits | Details |
|----------|-------------------|----------|--|
| 30604 | Starter state | 0 to 4 | 0 = Reserved |
| | | | 1 = Ready |
| | | | 2 = Starting |
| | | | 3 = Running |
| | | | 4 = Stopping |
| | | | 5 = Not ready (restart delay, restart |
| | | | temperature check, run simulation, reset |
| | | | input is open) |
| | | | 6 = Tripped |
| | | | 7 = Programming mode |
| | | | 8 = Jog forward 9 = Jog reverse |
| | | 5 | 1 = Warning |
| | | 6 | 0 = Uninitialised |
| | | | 1 = Initialised |
| | | 7 | Command source |
| | | ' | 0 = Remote Keypad, Digital Input, Clock |
| | | | 1 = Network |
| | | 8 | 0 = Parameter(s) have changed since last |
| | | | parameter read |
| | | | 1 = No parameters have changed |
| | | 9 | 0 = Negative phase sequence |
| | | | 1 = Positive phase sequence |
| | | 10 to 15 | Reserved |
| 30605 | Current | 0 to 13 | Average rms current across all three phases |
| | | 14 to 15 | Reserved |
| 30606 | Current | 0 to 9 | Current (% motor FLC) |
| | | 10 to 15 | Reserved |
| 30607 | Motor temperature | 0 to 7 | Motor thermal model (%) |
| | | 8 to 15 | Reserved |
| 30608 | Power | 0 to 11 | Power |
| | | 12 to 13 | Power scale |
| | | | 0 = Multiply power by 10 to get W |
| | | | 1 = Multiply power by 100 to get W |
| | | | 2 = Power (kW) 3 = Multiply power by 10 to get kW |
| | | 14 to 15 | Reserved |
| 30609 | % Power factor | 0 to 7 | 100% = power factor of 1 |
| 00000 | 70 1 GWGI IGGIGI | 8 to 15 | Reserved |
| 30610 | Voltage | 0 to 13 | Average rms voltage across all three |
| 30010 | Voltago | | phases |
| | | 14 to 15 | Reserved |
| l . | | l . | |

| Register | Description | Bits | Details |
|-----------------|-------------------------------|----------|---|
| 30611 | Current | 0 to 13 | Phase 1 current (rms) |
| | | 14 to 15 | Reserved |
| 30612 | Current | 0 to 13 | Phase 2 current (rms) |
| | | 14 to 15 | Reserved |
| 30613 | Current | 0 to 13 | Phase 3 current (rms) |
| | | 14 to 15 | Reserved |
| 30614 | Voltage | 0 to 13 | Phase 1 voltage |
| | | 14 to 15 | Reserved |
| 30615 | Voltage | 0 to 13 | Phase 2 voltage |
| | | 14 to 15 | Reserved |
| 30616 | Voltage | 0 to 13 | Phase 3 voltage |
| | | 14 to 15 | Reserved |
| 30617 | Parameter list version number | 0 to 7 | Parameter list minor revision |
| | | 8 to 15 | Parameter list major version |
| 30618 | Digital input state | 0 to 15 | For all inputs, 0 = open, 1 = closed (shorted) 0 = Start/Stop 1 = Reserved 2 = Reset 3 = Input A 4 = Input B 5 to 15 = Reserved |
| 30619 | Trip code | 0 to 7 | |
| 30019 | Trip code | 8 to 15 | See <i>Trip codes</i> on page 20 Reserved |
| 30620 | Reserved | 0 10 13 | Neserveu |
| 30620 | Frequency | 0 to 15 | Frequency (Hz) |
| 30621 | Ground current | 0 to 15 | Ground current (A) |
| 30623~ 30631 | Reserved | 0 10 13 | Ground current (A) |



NOTICE

Reading register 30603 (Changed parameter value) will reset registers 30602 (Changed parameter number) and 30604 (Parameters have changed). Always read registers 30602 and 30604 before reading register 30603.



NOTICE

The reset input is normally closed by default. If parameter 7I *Reset/Enable Logic* is set to normally open, the reported state will be inverted (0 = closed, 1 = open).

Legacy mode

Registers



NOTICE

For models 0064B and smaller (soft starter model ID 1~4), current reported via communications is 10 times greater than the actual value (displayed on the keypad).



NOTICE

Legacy Mode reports read-only status information in registers 40003 onwards, to match the register definitions of the clip-on Modbus Module for use with older soft starters. Identical data is also available via registers 30003 onwards.

| Register | Description | Bits | Details |
|----------|---------------------------|----------------|--|
| 40001 | Reserved | | |
| 40002 | Command (single write) | 0 to 2 | To send a command to the starter, write the required value: 1 = Start 2 = Stop 3 = Reset 4 = Quick stop (coast to stop) 5 = Forced communication trip 6 = Start using Parameter Set 1 7 = Start using Parameter Set 2 |
| | | 3 to 15 | Reserved |
| 40003 | Starter state | 0 to 3 4 5 6 | 1 = Ready 2 = Starting 3 = Running 4 = Stopping (including braking) 5 = Restart delay (including temperature check) 6 = Tripped 7 = Programming mode 8 = Jog forward 9 = Jog reverse 1 = Positive phase sequence (only valid if bit 6 = 1) 1 = Current exceeds FLC 0 = Uninitialised 1 = Initialised |
| | | 7 to 15 | Reserved |
| 40004 | Reserved | | |
| 40005 | Motor current | 0 to 7 | Average rms current across all three phases |
| | | 8 to 15 | Reserved |
| 40006 | Motor temperature | 0 to 7 | Motor thermal model (%) |
| | | 8 to 15 | Reserved |
| 40007 | Reserved | | |
| 40008 | Reserved | | |

| | Description | Bits | Details | |
|---------|--|----------|--|--|
| ~ r | Parameter management (single or multiple | 0 to 7 | Manage soft starter programmable parameters. See the relevant soft starter literature for a complete parameter list. | |
| I I ' | read/write) | 8 to 15 | Reserved | |
| 40600 F | Product information | 0 to 5 | Binary protocol version | |
| | | 6 to 8 | Reserved | |
| | | 9 to 15 | Product type code: | |
| | | | 12 = n/a 13 = V6 | |
| 40601 | Model number | 0 to 7 | Reserved | |
| | | 8 to 15 | Soft starter model ID | |
| | Changed parameter number | 0 to 7 | 0 = No parameters have changed 1~255 = Index number of the last parameter changed | |
| | | 8 to 15 | Total number of parameters available in the starter | |
| | Changed parameter value | 0 to 15 | Value of the last parameter that was changed, as indicated in register 40602 | |
| 40604 | Starter state | 0 to 4 5 | <pre>0 = Reserved 1 = Ready 2 = Starting 3 = Running 4 = Stopping 5 = Not ready (restart delay, restart temperature check, run simulation, reset input is open) 6 = Tripped 7 = Programming mode 8 = Jog forward 9 = Jog reverse 1 = Warning 0 = Uninitialised 1 = Initialised</pre> | |
| | | 7 | Command source 0 = Remote Keypad, Digital Input, Clock 1 = Network 0 = Parameter(s) have changed since last | |
| | | O . | parameter read 1 = No parameters have changed | |
| | | 9 | 0 = Negative phase sequence 1 = Positive phase sequence | |
| | | 10 to 15 | Reserved | |
| 40605 | Current | 0 to 13 | Average rms current across all three phases | |
| | | 14 to 15 | Reserved | |
| 40606 | Current | 0 to 9 | Current (% motor FLC) | |
| | | 10 to 15 | Reserved | |

| Register | Description | Bits | Details | | |
|-----------------|------------------------|----------|--|--|--|
| 40607 | Motor temperature | 0 to 7 | Motor thermal model (%) | | |
| | | 8 to 15 | Reserved | | |
| 40608 | Power | 0 to 11 | Power | | |
| | | 12 to 13 | Power scale | | |
| | | | 0 = Multiply power by 10 to get W | | |
| | | | 1 = Multiply power by 100 to get W 2 = Power (kW) | | |
| | | | 3 = Multiply power by 10 to get kW | | |
| | | 14 to 15 | Reserved | | |
| 40609 | % Power factor | 0 to 7 | 100% = power factor of 1 | | |
| | | 8 to 15 | Reserved | | |
| 40610 | Voltage | 0 to 13 | Average rms voltage across all three phases | | |
| | | 14 to 15 | Reserved | | |
| 40611 | Current | 0 to 13 | Phase 1 current (rms) | | |
| | | | Reserved | | |
| 40612 | Current | 0 to 13 | Phase 2 current (rms) | | |
| | | 14 to 15 | Reserved | | |
| 40613 | 40613 Current | | Phase 3 current (rms) | | |
| | | 14 to 15 | Reserved | | |
| 40614 | Voltage | 0 to 13 | Phase 1 voltage | | |
| | | 14 to 15 | Reserved | | |
| 40615 | Voltage | 0 to 13 | Phase 2 voltage | | |
| | | 14 to 15 | Reserved | | |
| 40616 | Voltage | 0 to 13 | Phase 3 voltage | | |
| | | 14 to 15 | Reserved | | |
| 40617 | Parameter list version | 0 to 7 | Parameter list minor revision | | |
| | number | 8 to 15 | Parameter list major version | | |
| 40618 | Digital input state | 0 to 15 | For all inputs, 0 = open, 1 = closed (shorted) | | |
| | | | 0 = Start/Stop | | |
| | | | 1 = Reserved 2 = Reset | | |
| | | | 3 = Input A | | |
| | | | 4 = Input B | | |
| | | | 5 to 15 = Reserved | | |
| 40619 | Trip code | 0 to 7 | See <i>Trip codes</i> on page 20 | | |
| | | 8 to 15 | Reserved | | |
| 40620~ 40631 | Reserved | | | | |



NOTICE

Reading register 40603 (Changed parameter value) will reset registers 40602 (Changed parameter number) and 40604 (Parameters have changed). Always read registers 40602 and 40604 before reading register 40603.



NOTICE

The reset input is normally closed by default. If parameter 7I *Reset/Enable Logic* is set to normally open, the reported state will be inverted (0 = closed, 1 = open).

Examples

Command: Start

| Message | Starter Address | Function Code | Register Address | Data | CRC |
|---------|--------------------|------------------|---------------------|------|------------|
| In | 20 | 06 | 40002 | 1 | CRC1, CRC2 |
| Out | 20 | 06 | 40002 | 1 | CRC1,CRC 2 |

Starter state: Running

| Message | Starter Address | Function Code | Register Address | Data | CRC |
|---------|--------------------|------------------|---------------------|----------|------------|
| In | 20 | 03 | 40003 | 1 | CRC1, CRC2 |
| Out | 20 | 03 | 2 | xxxx0011 | CRC1, CRC2 |

Trip code: Motor overload

| Message | Starter Address | Function Code | Register Address | Data | CRC |
|---------|--------------------|------------------|---------------------|----------|------------|
| In | 20 | 03 | 40004 | 1 | CRC1, CRC2 |
| Out | 20 | 03 | 2 | 00000010 | CRC1, CRC2 |

Download parameter from starter

Read parameter 5 (1E Locked Rotor Current), 600%

| Message | Starter Address | Function Code | Register | Data | CRC |
|---------|--------------------|------------------|-----------|------|------------|
| In | 20 | 03 | 40013 | 1 | CRC1, CRC2 |
| Out | 20 | 03 | 2 (bytes) | 600 | CRC1, CRC2 |

Upload single parameter to starter

Write parameter 16 (2I Stop Mode), set = 1

| Message | Starter Address | Function Code | Register | Data | CRC |
|---------|--------------------|------------------|----------|------|------------|
| In | 20 | 06 | 40024 | 1 | CRC1, CRC2 |
| Out | 20 | 06 | 40024 | 1 | CRC1, CRC2 |

Upload multiple parameters to starter

Write Parameters 9, 10, 11 (parameters 2B *Start Ramp Time*, 2C *Initial Current*, 2D *Current Limit*). Set to values of 15 seconds, 300%, 350% respectively.

| Message | Starter Address | Function Code | Register | Data | CRC |
|---------|--------------------|------------------|----------|--------------|------------|
| In | 20 | 16 | 40017,3 | 15, 300, 350 | CRC1, CRC2 |
| Out | 20 | 16 | 40017,3 | 15, 300, 350 | CRC1, CRC2 |



NOTICE

This function can only be used to upload consecutive parameters. The Register field indicates the number of parameters to be uploaded, and the register number of the first parameter.

Trip codes

| Trip code | Description |
|--------------|---|
| 255 | No trip |
| 1 | Excess start time |
| 2 | Motor overload |
| 3 | Motor thermistor |
| 4 | Current imbalance |
| | |
| 5 | Frequency |
| 6 | Phase sequence |
| 7 | Overcurrent |
| 8 | Power loss |
| 9 | Undercurrent |
| 10 | Heatsink overtemperature |
| 11 | Motor connection |
| 12 | Input A trip |
| 13 | FLC too high |
| 14 | Unsupported option (function not available in inside delta) |
| 15 | Communications card fault |
| 16 | Network communication |
| 18 | Overvoltage |
| 19 | Undervoltage |
| 20 | Ground fault |
| 23 | Parameter out of range |
| 24 | Input B trip |
| 26 | L1 phase loss |
| 27 | L2 phase loss |
| 28 | L3 phase loss |
| 29 | L1-T1 shorted |

| Trip | Description |
|-------|--|
| code | |
| 30 | L2-T2 shorted |
| 31 | L3-T3 shorted |
| 33 | Time-overcurrent (Bypass overload) |
| 34 | SCR overtemperature |
| 35 | Battery/clock |
| 36 | Thermistor circuit |
| 47 | Overpower |
| 48 | Underpower |
| 56 | Keypad disconnected |
| 57 | Zero Speed Detect |
| 58 | SCR Itsm |
| 59 | Instantaneous overcurrent |
| 60 | Rating Capacity |
| 70 | Current Read Err L1 |
| 71 | Current Read Err L2 |
| 72 | Current Read Err L3 |
| 74 | Motor Connection T1 |
| 75 | Motor Connection T2 |
| 76 | Motor Connection T3 |
| 77 | Firing Fail P1 |
| 78 | Firing Fail P2 |
| 79 | Firing Fail P3 |
| 80 | VZC Fail P1 |
| 81 | VZC Fail P2 |
| 82 | VZC Fail P3 |
| 83 | Low Control Volts |
| 84~96 | Internal fault x. Contact your local supplier with the fault code (X). |

Modbus error codes

| Code | Description | Example | | | |
|------|-----------------------|---|--|--|--|
| 1 | Illegal function code | The adapter or starter does not support the requested function | | | |
| 2 | Illegal data address | The adapter or starter does not support the specified register address | | | |
| 3 | Illegal data value | The adapter or starter does not support one of the received data values | | | |
| 4 | Server error | An error occurred while trying to perform the requested function | | | |
| 6 | Server busy | The adapter is busy (for example writing parameters to the starter) | | | |

7 SPECIFICATIONS



Connections

| Soft starter |
|---|
| • Settings |
| Protocol Modbus RTU, AP ASCII |
| Address range 0 to 254 |
| Data rate (bps) |
| Parity None, Odd, Even, 10-bit |
| Timeout |
| Certification |
| CE EN 60947-4-2 |
| RoHS Compliant with EU Directive 2011/65/EU |



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