

V6

ACCESSORIES MANUAL

ETHERNET/IP BOARD



Programming and Software Manual

Edition: June 2023

Rev. A

ABOUT THIS DOCUMENT

COMPATIBILITY

This manual is suitable for Ethernet/IP Card with Ground Fault.

The Ethernet/IP Card is suitable for use with V6 soft starters.

The available features may vary according to the model and version of the starter.

This user manual is intended for use with version 2.x of the Ethernet/IP card. Version 1.x of the Ethernet/IP card does not support custom users or IoT operation.

DISCLAIMER

The examples and diagrams in this manual are included solely for illustrative purposes. The information contained in this manual is subject to change at any time and without prior notice. In no event will responsibility or liability be accepted for direct, indirect or consequential damages resulting from the use or application of this equipment.

Failure to follow the information and instructions in this manual will void the warranty.

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REVISIONS CONTROL

DATE	REVISION	DESCRIPTION
30/06/2023	Α	First edition.

EN

The equipment and technical documentation are periodically updated. Power Electronics reserves the right to modify all or part of the contents of this manual without previous notice. To consult the most updated information of this product, you may access our website www.power-electronics.com, where the latest version of this manual can be downloaded. The reproduction or distribution of the present manual is strictly forbidden, unless express authorization from Power Electronics.

SAFETY SYMBOLS

Always follow safety instructions to prevent accidents and potential hazards from occurring.

In this manual, safety messages are classified as follows:



NOTICE

Indicates a hazard that may cause personal injury or death.



CAUTION

Indicates a hazard that may damage the equipment or installation.



WARNING

Provides helpful information.

Other symbols used in this manual for safety messages are the following:



Hot surface. Be careful and follow the instructions to avoid burns and personal injuries.



Risk of fire. Be careful and follow the instructions to prevent causing an unintentional fire.



Energy storage timed discharge. Wait for the indicated time to avoid electrical hazards.



Caution, risk of hearing damage. Wear hearing protection.

Warnings

It is the installer's responsibility to follow all instructions in this manual and to follow correct electrical practice.



WARNING

For your safety, isolate the soft starter completely from mains voltage before attaching or removing accessories.



WARNING

Inserting foreign objects or touching the inside of the starter while the expansion port cover is open may endanger personnel, and can damage the starter.

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ΕN

1 INTRODUCTION

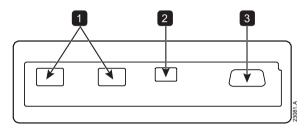


Product design

The Ethernet/IP Card allows the soft starter to connect to an Ethernet network and be controlled or monitored using an Ethernet communication model.

Familiarity with Ethernet protocols and networks is required to operate the device successfully. For difficulties using this device with third party products, including PLCs, scanners and commissioning tools, contact the relevant supplier.

Connections

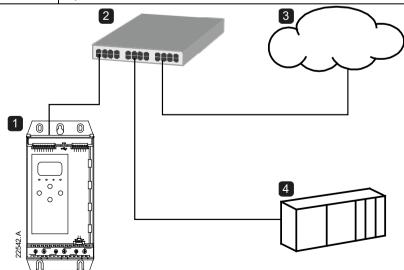


1	2 x RJ45 ethernet ports, supporting line, star, ring and loop network topologies
2	2 pin connector for ground fault CT (selected models)
3	DB9 connector for optional remote keypad

Communication protocols

The Ethernet/IP Card supports the following protocols:

Ethernet/IP	Industrial ethernet via Ethernet/IP
MQTT	Message Queue Telemetry Transport
OPC UA	Open Platform Communications Unified Architecture



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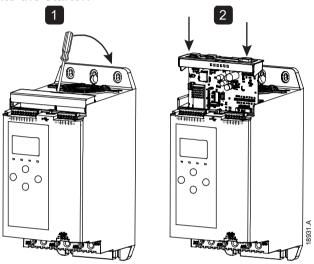
1	Soft starter
2	Network switch
3	IoT connection (MQTT/OPC UA)
4	Industrial ethernet connection to programmable logic controller

2 INSTALLATION



Installing the expansion card

- 1. Push a small flat-bladed screwdriver into the slot in the centre of the expansion port cover, and ease the cover away from the starter.
- 2. Line up the card with the expansion port. Gently push the card along the guide rails until it clicks into the starter.



Network connection

Ethernet ports

The device has two Ethernet ports. If only one connection is required, either port can be used.

Cables

Use Category 5, 5e, 6 or 6e cable to connect to the device.

EMC precautions

To minimise electromagnetic interference, Ethernet cables should be separated from motor and mains cables by 200 mm.

If the Ethernet cable must cross motor or mains cables, the crossing should be at an angle of 90°.

Network establishment

The controller must establish communications directly with each device before the device can participate in the network.

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Addressing

Each device in a network is addressed using a MAC address and an IP address.

• The device can be assigned a static IP address during configuration, or can be configured to accept a dynamic IP address (via DHCP).

 The MAC address is fixed within the device and is printed on a label on the front of the device.

3 DEVICE CONFIGURATION

3



NOTICE

The Error LED flashes whenever the device is receiving power but is not connected to a network. The Error LED will flash occasionally during the configuration process.



NOTICE

At power-up, the card loads the IP address stored in the soft starter.

Configuration methods

Network communication parameters for the card can be set via the soft starter or via the on-board web server.

- The card uses a static IP address by default. To enable DHCP addressing, set parameter 12T DHCP to 'Enable' or change the setting via the on-board web server.
- The IP address can be configured via the soft starter's programmable parameters.
- The web server can configure the IP address and messaging settings for MQTT or OPC UA operation.

Configure network settings via the starter

Use parameters 12H~12U to configure the network address. The parameters can be set via the Main Menu, via the Setup Tools, or by uploading a configuration file via USB Save & Load.

Parameter	Parameter name	Default
12H	Gateway Address	192
121	Gateway Address 2	168
12J	Gateway Address 3	0
12K	Gateway Address 4	100
12L	IP Address	192
12M	IP Address 2	168
12N	IP Address 3	0
120	IP Address 4	2
12P	Subnet Mask	255
12Q	Subnet Mask 2	255
12R	Subnet Mask 3	255
12S	Subnet Mask 4	0
12T	DHCP	Disable
12U	Location ID	0

Enabling network control

The soft starter will only accept commands from the Ethernet/IP Card if parameter 1A Command Source is set to 'Network'.



NOTICE

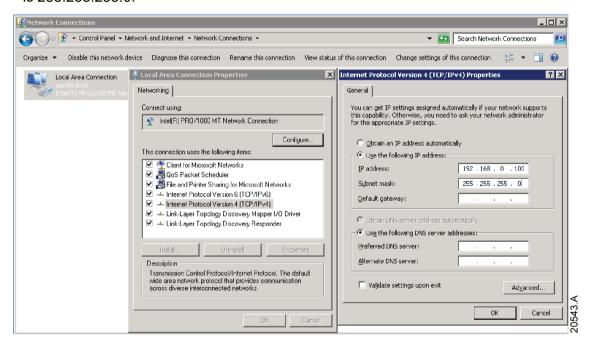
If the reset input is active, the starter will not operate. If a reset switch is not required, use parameter 7I to set the reset input to normally open or fit a link across terminals 10, 11 on the soft starter.

On-board web server

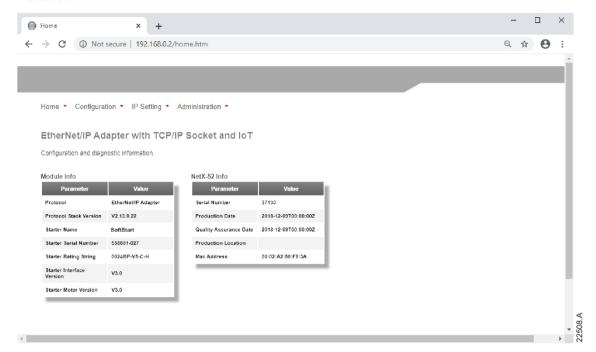
Connect to the device

To configure settings using the on-board web server, the card must be installed in a soft starter, control power must be available, and the card and computer must both be connected to the Ethernet network.

The computer must use a fixed IP address (not DHCP) and the same subnet mask as the card. The default IP address for the card is 192.168.0.2. The default subnet mask is 255.255.255.0.



Once connected, the web server reports basic information about the card and the soft starter.



Manage users and passwords



NOTICE

For security reasons, we recommend that you define a custom administrator ID and password.

The default username and password are:

username: admin password: 1978



NOTICE

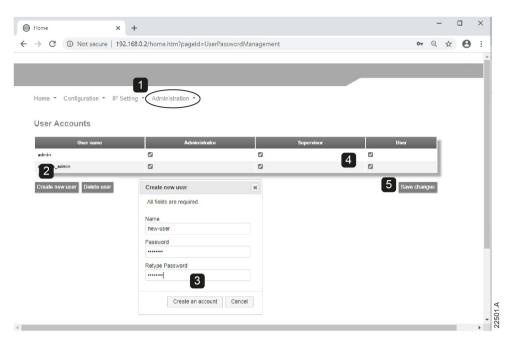
Version 1.x of the Ethernet/IP Card does not support custom users.

The Ethernet/IP Card supports multiple users and levels of privilege.

- Users can view the home screen and IP address settings
- Supervisors can view the home screen and IP settings and can change configuration settings
- Administrators can view the home screen, change configuration settings and add or delete users

To add a new user:

- Connect to the web server then click Administration.
- 2. Click Create new user.
- 3. Enter the new username and password then click Create an account.
- 4. Set privileges (user, supervisor, administrator) as appropriate.
- 5. Click Save changes.



To delete a user:

- 1. Connect to the web server then click Administration.
- 2. Click the required entry in the user list then click Delete user. Click Delete again to confirm the action.

Configure the IP address



NOTICE

For version 1.x of the Ethernet/IP Card, changes made via the web server are not stored in the soft starter and will be lost when control power is cycled.

- 1. Connect to the web server then click IP Setting.
- 2. Edit the settings as required. To enable DHCP addressing, tick the DHCP checkbox.
- Click Submit to send the new settings to the device.



Configure IoT settings

The Ethernet/IP Card supports soft starter status monitoring over IoT. The card cannot control or program the soft starter.

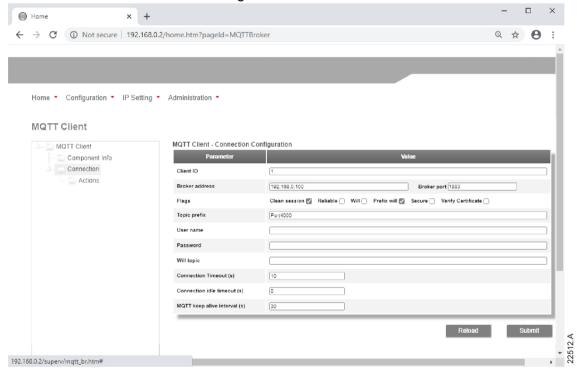


NOTICE

Version 1.x of the Ethernet/IP Card does not support IoT operation.

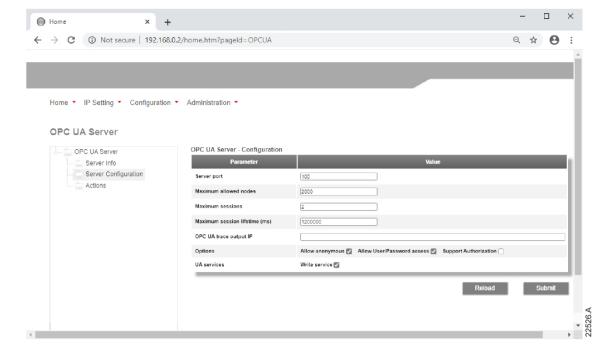
• Configure MQTT settings

- 1. Connect to the web server then click Configuration > MQTT Client.
- 2. Tick the Enable checkbox to enable MQTT client operation. The MQTT client is enabled by default.
- 3. Click Connection then configure the settings as required.
- 4. Use Connection > Actions to select which information the card will publish.
- 5. Click Submit to save all settings in the card.



Configure OPC UA settings

- Connect to the web server then click Configuration > OPC UA Server.
- 2. Tick the Enable checkbox to enable OPC UA client operation. The OPC UA client is enabled by default.
- Click Server Configuration then configure the settings as required.
- 4. Use Actions to select the actions for different object instances.
- 5. Click Submit to save all settings in the card.



Scanning the network

If you cannot connect to the web server and cannot physically access the soft starter, use the Ethernet Device Configuration software to scan the network and identify the device. Changes made via the software cannot be stored permanently in the device and will be lost when control power is cycled.

The Ethernet Device Configuration Tool is available from your local supplier.

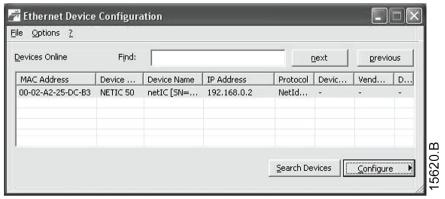


NOTICE

If your PC has a firewall enabled, you must add the tool to the list of authorised programs.

To identify the device using the Ethernet Device Configuration Tool:

- Start the Ethernet Device Configuration Tool.
- 2. Click on Search Devices. The software will search for connected devices.



3. Use the IP address to connect to the device via the web server.

4 SCANNER CONFIGURATION



EDS file

An EDS file that contains all required attributes of the device is available from your supplier.

Once the EDS file has been loaded, the individual device must be defined.

Assembly objects

The device supports two assembly objects.

Description	Class	Instance	Туре	Maximum size
Output (scanner -> starter)	04d (0x04)	100d (0x64)	Integer	2 (4 bytes)
Input (starter -> scanner)	04d (0x04)	101d (0x65)	Integer	6 (12 bytes)

5 GROUND FAULT PROTECTION

5



NOTICE

Ground fault protection is only available on ground fault enabled cards, with soft starters running a compatible version of software. Contact your supplier for assistance.

Overview

The Ethernet/IP Card can detect ground current and trip before the equipment is damaged.

Ground fault protection requires a 1000:1 or 2000:1 current transformer (not supplied). The CT should be rated 1 VA or 5 VA. The soft starter can be configured to trip at 1 A~50 A. If ground fault current rises above 50 A, the soft starter will trip immediately.

Parameter 40C Ground Fault Trip Active selects when ground fault protection is active.

Connect the CT to the ground fault inputs

To use ground fault protection, a common mode current transformer (CT) must be installed around all three phases. Use a 1000:1 or 2000:1 CT with rating of 1 VA or 5 VA and set parameter 40E *Ground Fault CT Ratio* to match. Connect the CT to the ground fault terminals (G1, G2, G3).

For maximum protection, the CT should be installed on the input side of the soft starter.

Configure ground fault protection settings

Ground fault protection settings must be set in the soft starter.

Parameter	Parameter name	Description
40A	Ground Fault Level	Sets the trip point for ground fault protection.
40B	Ground Fault Delay	Slows the Ethernet/IP Card's response to ground fault variation, avoiding trips due to momentary fluctuations.
40C	Ground Fault Trip Active	Selects when a ground fault trip can occur.
40D	Ground Fault Action	Selects the soft starter's response to the protection event.
40E	Ground Fault CT Ratio	Set to match the ratio of the ground current measuring CT.

6 OPERATION



The Ethernet/IP Card is conformance tested to ODVA. For successful operation, the scanner must also support all functions and interfaces described in this document.



NOTICE

The available features and parameter details may vary according to the model and software version of the starter. Refer to the soft starter user manual for details of parameters and supported features.

Device classification

The Ethernet/IP Card is an I/O Adapter and must be managed by an I/O Scanner over Ethernet.

The Ethernet/IP Card supports both implicit (cyclic) and explicit (acyclic) messaging.

Ensuring safe and successful control

Data written to the device will remain in its registers until the data is overwritten or the device is reinitialised.

If the soft starter may be controlled via Command Override (parameter 7A) or may be disabled via the reset input (terminals 10, 11) fieldbus commands should be cleared from the registers. If a command is not cleared, it will be re-sent to the starter once fieldbus control resumes.

Feedback LEDs



LED name	LED state	Description
Error	Off	Device is not powered up or has received an IP address.
	Flashing	Connection timeout.
	On	Duplicate IP address.
Status	Off	Device is not powered up or has received an IP address.
	Flashing	Device has obtained an IP address but has not established any network connections.
	On	Communication has been established.
Link x	Off	No network connection.
	On	Connected to a network.
TX/RX x	Flashing	Transmitting or receiving data.

This section lists requirements related to cyclic (implicit messaging) services for the Ethernet/IP Card.

The minimum cyclic interval is 1 ms.

All data is in little endian format.

Assembly objects

The device supports two assembly objects.

Description	Class	Instance	Туре	Maximum size
Output (scanner -> starter)	04d (0x04)	100d (0x64)	Integer	2 (4 bytes)
Input (starter -> scanner)	04d (0x04)	101d (0x65)	Integer	6 (12 bytes)

Control commands (assembly instance 100d)

To send control data from the scanner to the starter, use assembly class 04d (0x04), assembly instance 100d (0x64), attribute 03d (0x03).

Bytes 0-1: Command

Bits	Function	Details
0 to 5	Reserved	Must be zero
6	Run	0 = Stop command
		1 = Start command
7	Reset	Changing this bit from 0 to 1 will reset a trip.
8 to 12	Reserved	Must be zero
13	Motor set	0 = Use primary motor set when starting
	select	1 = Use secondary motor set when starting
14 to 15	Reserved	Must be zero

Bytes 2-3: Reserved

Bits	Function	Details
0 to 15	Reserved	Must be zero

Command examples

Byte	Value	Description
0	0b01000000 (64d, 0x40)	Start the soft starter

Byte	Value	Description
1	0b00000000 (00d, 0x00) or	Use primary motor set when starting
	0b00100000 (32d, 0x20)	Use secondary motor set when starting
0	0b10000000 (128d, 0x80)	Reset the soft starter
		The reset only occurs when the previous reset bit is zero, otherwise the value of 1 will be ignored.
0	0b11000000 (192d, 0xC0)	Reset and start the soft starter
0	0bX0000000 (00d, 0x00)	Stop the soft starter

Status information (assembly instance 101d)

To retrieve status data from the starter, use assembly class 04d (0x04), assembly instance 101d (0x65), attribute 03d (0x03).

Bytes 0-1: Starter state

Bits	Function	Details
0	Ready	0 = Not ready
		1 = Ready to start
1	Operating	0 = Program mode
	mode	1 = Operating mode
2	Running	0 = Not ready, Ready to start or Tripped
		1 = Starting, Running, Stopping or Jogging
3	Trip	0 = Not tripped
		1 = Tripped
4	Jog forward	1 = Jog forward
5	Jog reverse	1 = Jog reverse
6	Reserved	
7	Warning	0 = No warning
		1 = Warning
8	Ramping	1 = Running (full voltage at the motor)
9	Command	0 = Remote Keypad, Digital Input, Clock
	source	1 = Network
10	Reserved	
11	Reserved	
12	Reserved	
13	Reserved	
14	Reserved	
15	Temperature	0 = Motor operating within thermal capacity (thermal model)
	limit	1 = Motor operating above thermal capacity (thermal
		model)

Bytes 2-3: Reserved

Bits	Function	Details
0 to 15	Reserved	

Bytes 4-7: Motor current

Bits	Function	Details
0 to 31	Motor current	Average rms current across all three phases. Measured current is represented as a 32-bit value to 2 decimal places. 10d (0x0A) = 0.10 A 3450d (0xD7A) = 34.50 A 68930d (0x10D42) = 689.30 A

Bytes 8-9: Trip code

Bits	Function	Details
0 to 15	Trip code	See <i>Trip codes</i> on page 26

Bytes 10-11: Reserved

Bits	Function	Details
0 to 15	Reserved	

ΕN

8 EXPLICIT MESSAGING (ACYCLIC OPERATION)



This section provides information on objects, instances, attributes and services for acyclic operation (explicit messaging).

All data is in little endian format.

Identity object (class 0x01)

The Ethernet/IP Card supports the following attributes for identity objects:

Attribute	Function	Value
1	Vendor	204d (0xCC)
2	Device type	12d (0x0C)
3	Product code	269d (0x10D)
4	Revision: Major, Minor	EDS file version
5	Status	Supported
6	Serial number	Supported
7	Product name	Supported

Vendor-specific objects

The Ethernet/IP Card supports vendor-specific classes 100, 101, 102, 103 and 104.

Class 100~102 objects (read/write)

Class 100~102 objects allow parameter values to be read from and written to the soft starter.

- Class 100d (0x64): parameters 1~99
- Class 101d (0x65): parameters 100~199
- Class 102d (0x66): parameters 200~299



NOTICE

Parameter lists vary according to the model and version of soft starter. See the relevant soft starter literature for a complete parameter list.

Class 103 objects (read only)

Class 103d (0x67) allows starter state information to be read from the soft starter.

Object name	Class	Instance	Attribute
Binary protocol version	103	100	100
Product type code	103	101	100
Reserved	103	102	100
Reserved	103	103	100
Soft starter model	103	104	100
Changed parameter number	103	105	100
Number of parameters	103	106	100
Changed parameter value	103	107	100
Reserved	103	108	100
Starter state 1 = Ready 2 = Starting 3 = Running 4 = Stopping (including braking) 5 = Restart delay (including temperature check) 6 = Tripped 7 = Programming mode 8 = Jog forward 9 = Jog reverse	103	109	100
Warning 1 = Warning, 0 = No warning	103	110	100
Initialised 1 = Phase sequence is valid	103	111	100
Phase sequence (1 = Positive phase sequence, only valid if Initialised =1)	103	112	100
Reserved	103	113	100
Reserved	103	114	100
Trip/Warning code (See <i>Trip codes</i> on page 26)	103	115	100
Average rms current across all three phases	103	116	100
Current (% motor FLC)	103	117	100
Motor temperature	103	118	100
Reserved	103	119	100
Power	103	120	100
Power scale 0 = Multiply power by 10 to get W 1 = Multiply power by 100 to get W 2 = Power (kW) 3 = Multiply power by 10 to get kW	103	121	100
% Power factor	103	122	100
Average rms voltage across all three phases	103	123	100

Object name	Class	Instance	Attribute
Phase 1 current	103	124	100
Phase 2 current	103	125	100
Phase 3 current	103	126	100
Phase 1 voltage	103	127	100
Phase 2 voltage	103	128	100
Phase 3 voltage	103	129	100
Parameter list minor revision	103	130	100
Parameter list major version	103	131	100
Digital input state	103	132	100
For all inputs, 0 = open, 1 = closed (shorted)			
Start/stop input = 01h, Reset = 04h, Programmable			
input A = 08h, Programmable input B = 10h			
Trip code	103	133	100
Reserved	103	134	100
Frequency	103	135	100
Ground current	103	136	100



NOTICE

The reset input is normally closed by default. If parameter 7I *Reset/Enable Logic* is set to normally open, the reported state will be inverted (0 = closed, 1 = open).



NOTICE

For models 0064B and smaller, current reported via communications is 10 times greater than the actual value (displayed on the keypad).



NOTICE

Frequency reported via communications is 10 times greater than the actual value.

Class 104 objects (read only)

Class 104d (0x68) allows extended information to be read from the soft starter.

Object name	Class	Instance	Attribute
Major Software Version – User interface	104	101	100
Minor Software Version – User interface	104	102	100
Major Software Version – Motor control	104	103	100
Minor Software Version – Motor control	104	104	100
Major Software Version – Remote keypad (if installed)	104	105	100
Minor Software Version – Remote keypad (if installed)	104	106	100

POWER ELECTRONICS V6

Supported services for vendor-specific objects

This section describes the operational instructions to carry out acyclic services on class objects 100, 101, 102, 103 and 104.

Service codes for acyclic operation

The device supports the following services for vendor-specific objects:

Service code	Function	Description
01d (0x01)	Get Attribute All	Only supported for class 0x01 identity object
10d (0x10)	Set Attribute Single	Supported
15d (0x0E)	Get Attribute Single	Supported

Status codes for acyclic services

The device will return the following status codes in response to Get/Set Attribute Single:

Status code	Status name	Details		
00d (0x00)	Success	This code is returned when:		
		 the register mapped for service 'Get Attribute Single' is successfully read 		
		the register mapped for service 'Set Attribute Single' is successfully set		
03d (0x03)	Invalid parameter value			
05d (0x05)	Path destination unknown	The mapped register does not exist.		
08d (0x08)	Service not supported	The requested service is not available for this Object Class/Instance.		
09d (0x09)	Invalid attribute value	This code only applies to the service 'Set Attribute Single'. It is returned if the value is out of range for the mapped register.		
15d (0x0E)	Attribute not settable	This code only applies to the service 'Set Attribute Single'. It is returned if the mapped register is read-only.		
20d (0x14)	Attribute not supported	The attribute specified in the request is not supported.		
22d (0x16)	Object does not exist	The object specified does not exist in the device.		

ΕN

9 TRIP CODES

Code	Trip type
0	No trip
11	Input A trip
20	Motor overload
21	Heatsink overtemperature
23	L1 phase loss
24	L2 phase loss
25	L3 phase loss
26	Current imbalance
27	Ground fault
28	Overcurrent
29	Undercurrent
50	Power loss
51	Undervoltage
52	Overvoltage
54	Phase sequence
55	Frequency
60	Incorrect control card
61	FLC out of range
62	EEPROM fail (Parameter out of range)
75	Motor thermistor
101	Excess start time
102	Motor connection
104	Internal fault
110	Input B trip
113	Communications card fault
114	Network communication
115	L1-T1 shorted
116	L2-T2 shorted
117	L3-T3 shorted
119	Bypass overload
120	SCR overtemperature
121	Battery/clock
122	Thermistor circuit
124	RTD/PT100 B
133	Overpower

Code	Trip type
134	Underpower
142	Keypad disconnected
143	Zero Speed Detect
144	SCR Itsm
145	Instantaneous overcurrent
146	Rating Capacity
156	Current Read Err L1
157	Current Read Err L2
158	Current Read Err L3
160	Motor Connection T1
161	Motor Connection T2
162	Motor Connection T3
163	Firing Fail P1
164	Firing Fail P2
165	Firing Fail P3
166	VZC Fail P1
167	VZC Fail P2
168	VZC Fail P3
169	Low Control Volts
170~182	Internal fault x. Contact your local supplier with the fault code (X).

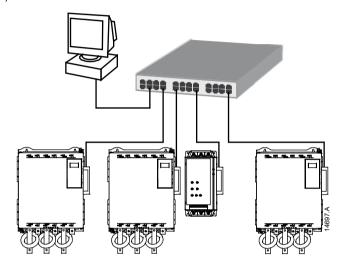
10 NETWORK DESIGN



The device supports star, line and ring topologies.

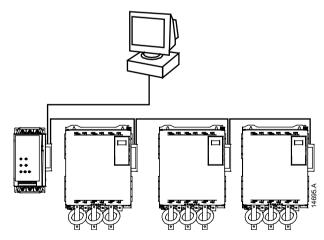
Star topology

In a star network, all controllers and devices connect to a central network switch.



Line topology

In a line network, the controller connects directly to one port of the first device. The second Ethernet port connects to another device, which in turn connects to another device until all devices are connected.





NOTICE

The device has an integrated switch to allow data to pass through in line topology. The device must be receiving control power from the soft starter for the switch to operate.



NOTICE

If the connection between two devices is interrupted, the controller cannot communicate with devices after the interruption point.



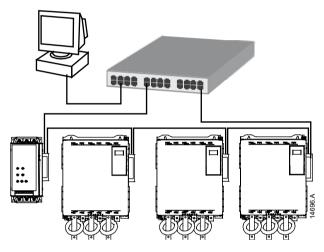
NOTICE

Each connection adds a delay to communication with the next device. The maximum number of devices in a line network is 32. Exceeding this number may reduce the reliability of the network.

Ring topology

In a ring topology network, the controller connects to the first card, via a network switch. The second Ethernet port of the card connects to another device, which in turn connects to another device until all devices are connected. The final device connects back to the switch.

The device supports beacon based ring node configuration with DLR (device level ring) redundancy.





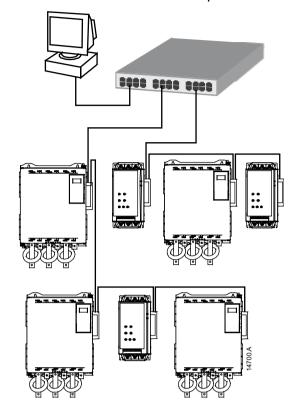
NOTICE

The network switch must support loss of line detection.

<u>EN</u>

Combined topologies

A single network can include both star and line components.



11 SPECIFICATIONS



Connections

Soft starter	6-way pin assembly
Contacts	Gold flash
Network	RJ45

Settings

Network

• Power

Certification

CE EN 60947-4-2

ODVA EtherNet ✓ IP
conformance tested



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